

Designation: E2582 - 07 (Reapproved 2014)

Standard Practice for Infrared Flash Thermography of Composite Panels and Repair Patches Used in Aerospace Applications¹

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This standard has been approved for use by agencies of the U.S. Department of Defense.

1. Scope

- 1.1 This practice describes a procedure for detecting subsurface flaws in composite panels and repair patches using Flash Thermography (FT), in which an infrared (IR) camera is used to detect anomalous cooling behavior of a sample surface after it has been heated with a spatially uniform light pulse from a flash lamp array.
- 1.2 This practice describes established FT test methods that are currently used by industry, and have demonstrated utility in quality assurance of composite structures during postmanufacturing and in-service examinations.
- 1.3 This practice has utility for testing of polymer composite panels and repair patches containing, but not limited to, bismaleimide, epoxy, phenolic, poly(amide imide), polybenzimidazole, polyester (thermosetting and thermoplastic), poly(ether ether ketone), poly(ether imide), polyimide (thermosetting and thermoplastic), poly(phenylene sulfide), or polysulfone matrices; and alumina, aramid, boron, carbon, glass, quartz, or silicon carbide fibers. Typical asfabricated geometries include uniaxial, cross ply and angle ply laminates; as well as honeycomb core sandwich core materials.
- 1.4 This practice has utility for testing of ceramic matrix composite panels containing, but not limited to, silicon carbide, silicon nitride and carbon matrix and fibers.
- 1.5 This practice applies to polymer or ceramic matrix composite structures with inspection surfaces that are sufficiently optically opaque to absorb incident light, and that have sufficient emissivity to allow monitoring of the surface temperature with an IR camera. Excessively thick samples, or samples with low thermal diffusivities, require long acquisition periods and yield weak signals approaching background and noise levels, and may be impractical for this technique.
- ¹ This practice is under the jurisdiction of ASTM Committee E07 on Nondestructive Testing and is the direct responsibility of Subcommittee E07.10 on Specialized NDT Methods.
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- 1.6 This practice applies to detection of flaws in a composite panel or repair patch, or at the bonded interface between the panel and a supporting sandwich core or solid substrate. It does not apply to discontinuities in the sandwich core, or at the interface between the sandwich core and a second panel on the far side of the core (with respect to the inspection apparatus).
- 1.7 This practice does not specify accept-reject criteria and is not intended to be used as a basis for approving composite structures for service.
- 1.8 This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.

2. Referenced Documents

2.1 ASTM Standards:²

D3878 Terminology for Composite Materials E1316 Terminology for Nondestructive Examinations

3. Terminology

- 3.1 *Definitions*—Terminology in accordance with Terminologies D3878 and E1316 and shall be used where applicable.
 - 3.2 Definitions of Terms Specific to This Standard:
- 3.2.1 *aspect ratio*—the diameter to depth ratio of a flaw. For irregularly shaped flaws, diameter refers to the minor axis of an equivalent rectangle that approximates the flaw shape and area.
- 3.2.2 *discrete discontinuity*—a thermal discontinuity whose projection onto the inspection surface is smaller than the field of view of the inspection apparatus.
- 3.2.3 extended discontinuity—a thermal discontinuity whose projection onto the inspection surface completely fills the field of view of the inspection apparatus.

² For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

- 3.2.4 *first logarithmic derivative*—the rate of change of the natural logarithm of temperature (with preflash temperature subtracted) with respect to the natural logarithm of time.
- 3.2.5 *inspection surface*—the surface of the specimen that is exposed to the FT apparatus.
- 3.2.6 *logarithmic temperature-time plot*—a plot of the natural logarithm of the surface temperature with preflash temperature subtracted on the y-axis versus the natural logarithm of time on the x-axis, where time t=0 is taken to be the midpoint of the flash event. Either temperature or radiance may be used to create the plot.
 - 3.2.7 *log plot*—see *logarithmic temperature-time plot*.
- 3.2.8 second logarithmic derivative—the rate of change of the first logarithmic derivative with respect to the natural logarithm of time.
- 3.2.9 *thermal diffusivity*—the ratio of thermal conductivity to the product of density and specific heat; a measure of the rate at which heat propagates in a material; units [length²/time].
- 3.2.10 *thermal discontinuity*—a change in the thermophysical properties of a specimen that disrupts the diffusion of heat.

4. Summary of Practice

- 4.1 In FT, a brief pulse of light energy from a flash lamp array heats the inspection surface of a composite specimen, and an IR camera monitors the surface temperature (or radiance) as the sample cools. The surface temperature falls predictably as heat from the surface diffuses into the sample bulk. However, internal thermal discontinuities (for example, voids, delaminations or a wall or interface between the host material and a void or inclusion) modify the local cooling of the surface, and the corresponding radiation flux from the surface that is detected by the IR camera.
- 4.2 Fundamental detectability of a flaw will depend on its size, depth, and the degree to which its thermal properties differ from those of the surrounding host material. For a given flaw-host combination, detectability is a function of the aspect ratio of the flaw. The minimum detectable flaw size increases with the depth of the flaw. Detectability is highest for larger flaws that are closer to the sample surface and have thermal properties that are significantly different from the host matrix material.
- 4.3 Operational parameters affecting detectability include component surface emissivity and optical reflectivity, data acquisition period, flash lamp energy, and camera wavelength, frame rate, sensitivity, optics and spatial resolution.
- 4.4 This practice describes a single-side access examination, in which the flash lamp array (excitation source) and IR camera (temperature sensor) are both located on the same (inspection) side of the component or material under examination.
- 4.5 In common practice, signal processing algorithms are used to enhance detectability of flaws that are not detectable in the raw IR camera signal, and to assist in evaluation and characterization of indications.

5. Significance and Use

- 5.1 FT is typically used to identify flaws that occur in the manufacture of composite structures, or to track flaw development during service. Flaws detected with FT include delamination, disbonds, voids, inclusions, foreign object debris, porosity or the presence of water that is in contact with the back surface. With dedicated signal processing and the use of representative test samples, characterization of flaw depth and size, or measurement of component thickness and thermal diffusivity may be performed.
- 5.2 Since FT is based on the diffusion of thermal energy from the inspection surface of the specimen to the opposing surface (or the depth plane of interest), the practice requires that data acquisition allows sufficient time for this process to occur, and that at the completion of the acquisition process, the radiated surface temperature signal collected by the IR camera is strong enough to be distinguished from spurious IR contributions from background sources or system noise.
- 5.3 This method is based on accurate detection of changes in the emitted IR energy emanating from the inspection surface during the cooling process. As the emissivity of the inspection surface deviates from ideal blackbody behavior (emissivity = 1), the signal detected by the IR camera may include components that are reflected from the inspection surface. Most composite materials can be examined without special surface preparation. However, it may be necessary to coat low-emissivity, optically translucent inspection surfaces with an optically opaque, high-emissivity water-washable paint.
- 5.4 This practice applies to the detection of flaws with aspect ratio greater than one.
- 5.5 This practice is based on the thermal response of a specimen to a light pulse that is uniformly distributed over the plane of the inspection surface. To ensure that 1- dimensional heat flow from the surface into the sample is the primary cooling mechanism during the data acquisition period, the height and width dimensions of the heated area should be significantly greater than the thickness of the specimen, or the depth plane of interest.
- 5.6 This practice applies to flat panels, or to curved panels where the local surface normal is less than 30 degrees from the IR camera optical axis

6. Equipment and Materials

6.1 IR Camera—The camera should be capable of uninterrupted monitoring of the sample surface for the entire duration of the acquisition. Cameras with automatic internal shuttering mechanisms should allow the shuttering to be disabled during the data acquisition period. The camera should provide real-time digital output of the acquired signal. The camera output signal should be approximately linear over the (post-flash) temperature range of the sample. The camera wavelength should be in either the 2-5 micron range or the 8-14 micron range, selected such that the test material is not IR translucent in the spectral range of the camera. The optics and focal plane should be sufficient so that the projection of nine contiguous pixels onto the sample plane is less than or equal to the minimum flaw area that is to be detected.